



# Queue

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- ▶ First in, first out (FIFO)
- ▶ Easily implemented with a List
  - ▶ Also LIFO!



# Priority Queue

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- ▶ **Prioritization problems**
- ▶ **Canonical example: ER scheduling**
  - ▶ A gunshot victim should probably get treatment sooner than that one guy with a sore neck, regardless of arrival time. How do we always choose the most urgent case when new patients continue to arrive?



# Poor choices

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- ▶ **list**

- ▶ remove max by searching is  $O(N)$

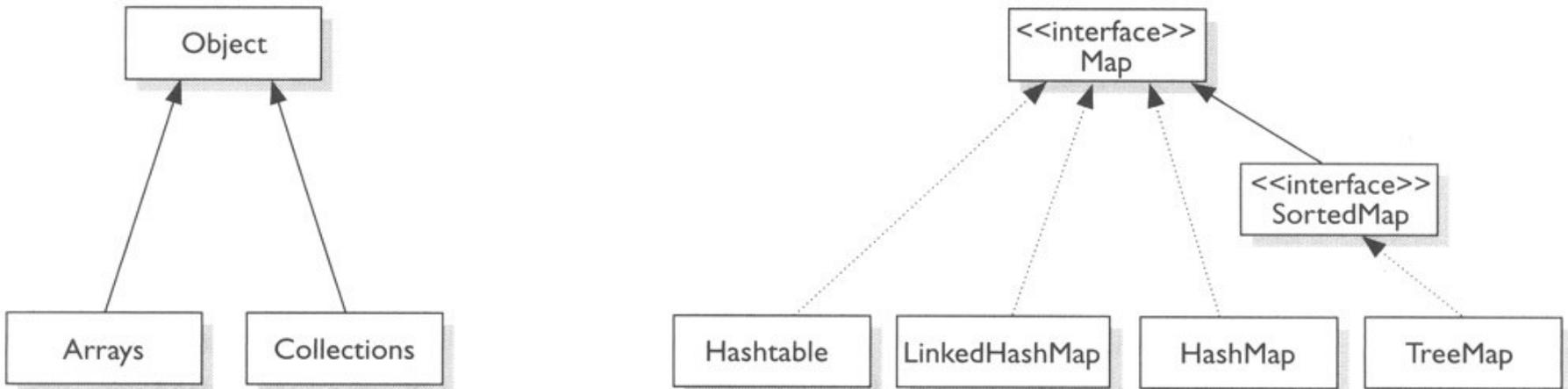
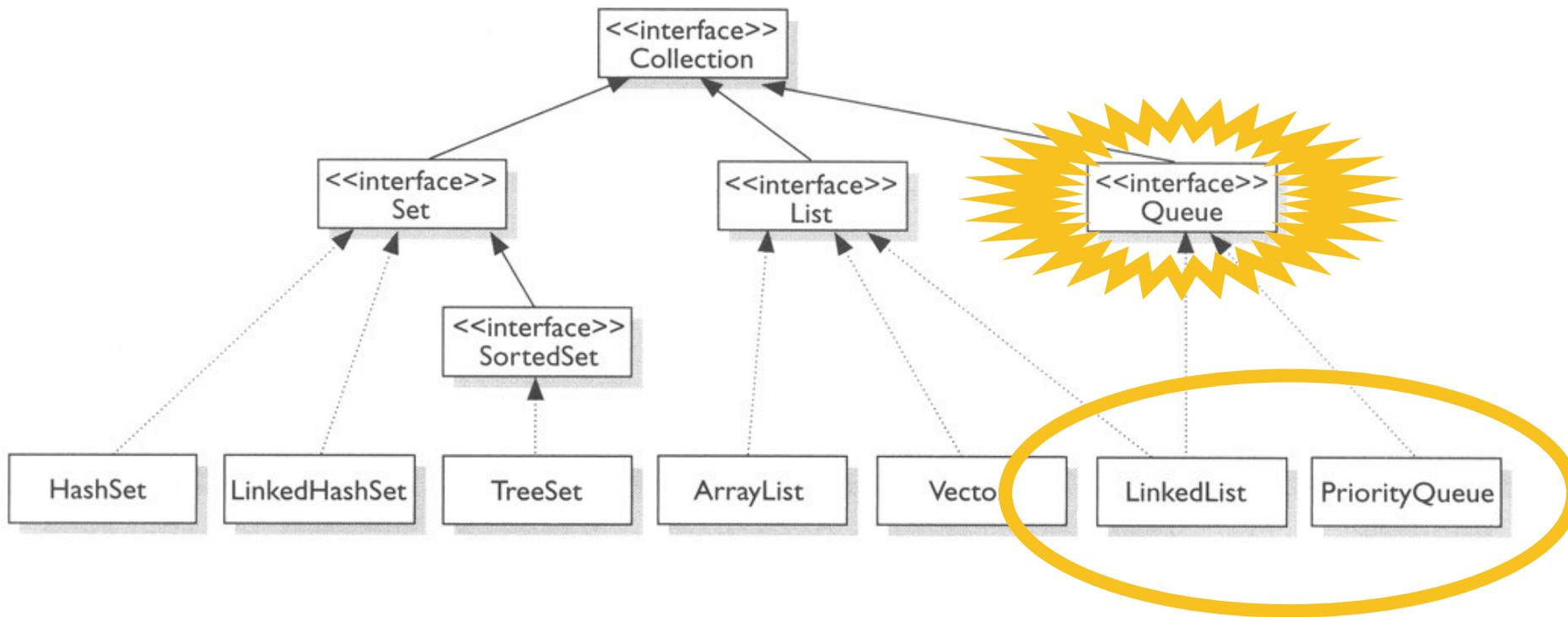
- ▶ **sorted list**

- ▶ remove max is  $O(1)$ ; add (remove) is  $O(N)$

- ▶ **binary search tree**

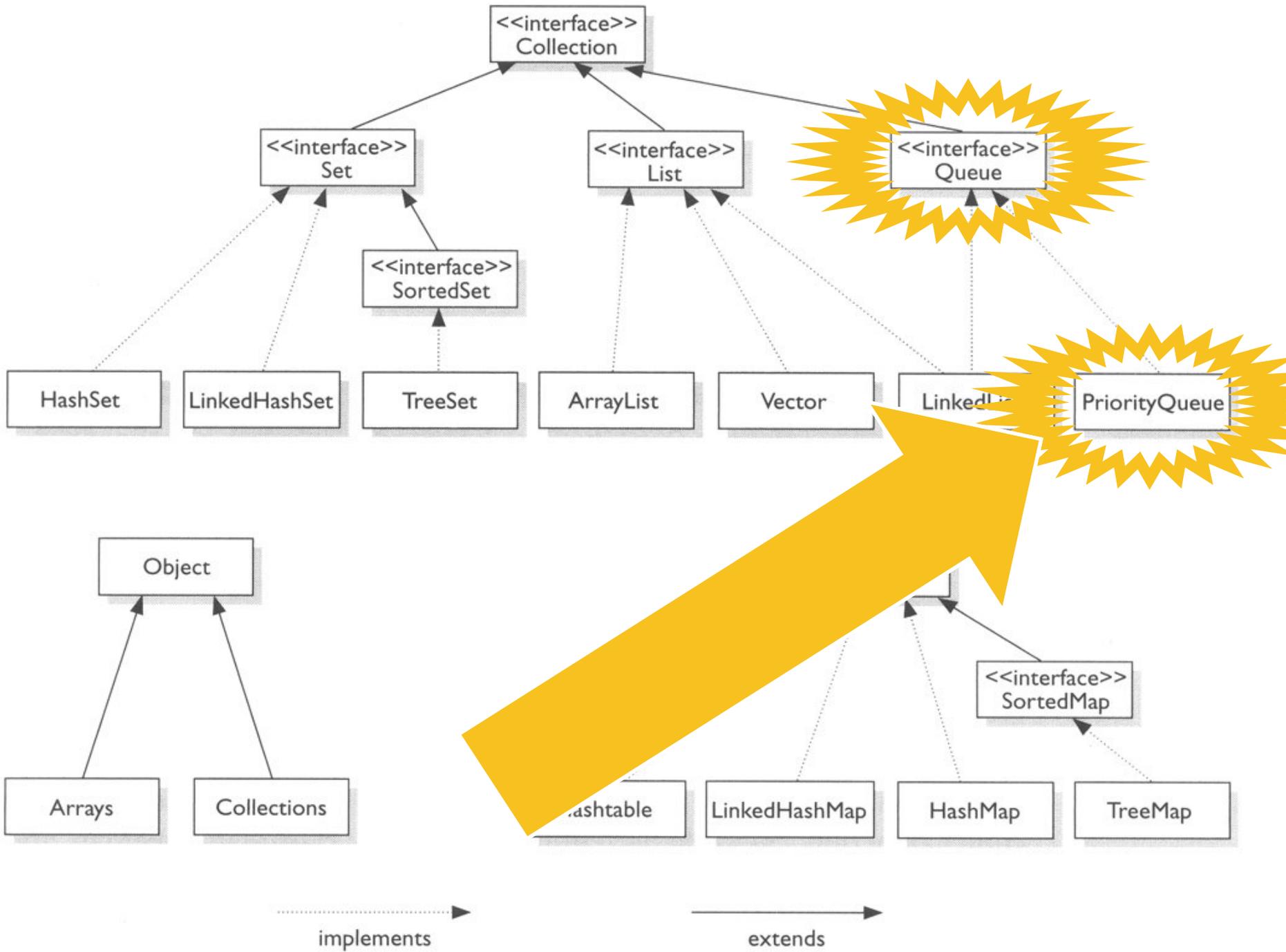
- ▶ remove max, add and remove are  $O(\log N)$
- ▶ ... but tree may become unbalanced





.....>  
implements

————>  
extends



# Queue interface

- ▶ Add elements
  - ▶ **boolean add(element)**
  - ▶ **boolean offer(element)**
- ▶ Remove elements
  - ▶ **element remove()**
  - ▶ **element poll()**
- ▶ Examine
  - ▶ **element element()**
  - ▶ **element peek()**

Queue Interface Structure

Type of Operation	Throws exception	Returns special value
Insert	add (e)	offer (e)
Remove	remove ()	poll ()
Examine	element ()	peek ()



# Queues

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## ▶ Known implementing classes:

- ▶ ArrayBlockingQueue
- ▶ ArrayDeque
- ▶ ConcurrentLinkedQueue
- ▶ DelayQueue
- ▶ LinkedBlockingDeque
- ▶ LinkedBlockingQueue
- ▶ LinkedList
- ▶ PriorityBlockingQueue
- ▶ **PriorityQueue** ←
- ▶ SynchronousQueue

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Double ended queues support insertion and removal at both ends. The name *deque* is short for “double ended queue” and is usually pronounced “deck”



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- ▶ **PriorityBlockingQueue**
- ▶ PriorityQueue
- ▶ **SynchronousQueue**

Supports operations that wait for the queue to become non-empty when retrieving an element, and wait for space to become available in the queue when storing an element.  
**Useful only in concurrent (multithreaded) applications.**



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An unbounded thread-safe queue



# PriorityQueue

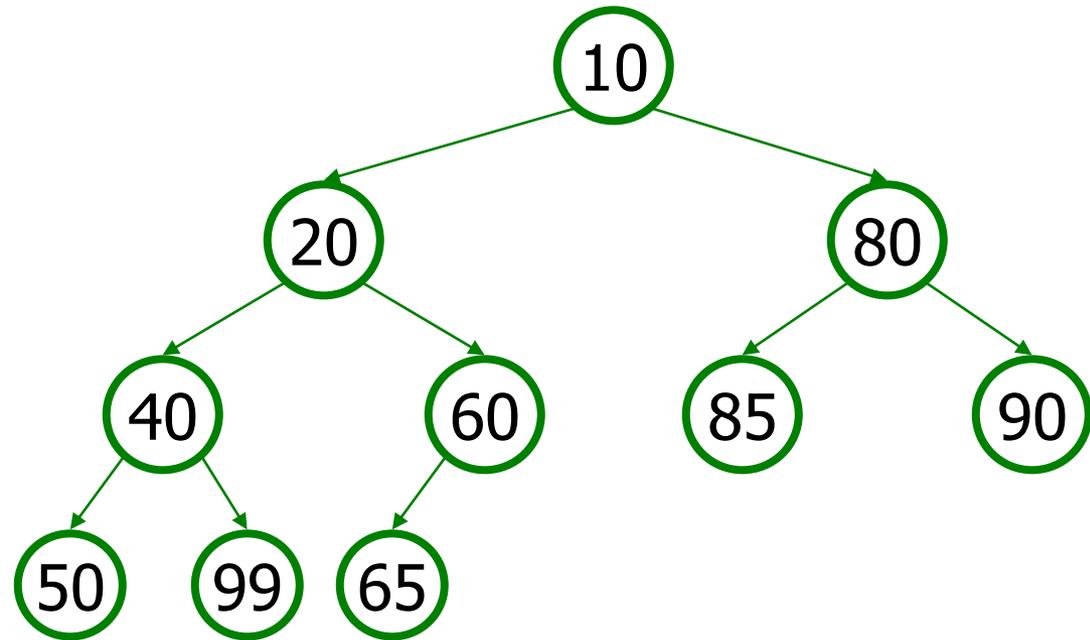
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- ▶ An unbounded priority queue based on a priority heap.

<b>Method/Constructor</b>	<b>Description</b>	<b>Runtime</b>
<code>PriorityQueue&lt;E&gt;()</code>	constructs new empty queue	$O(1)$
<code>add(E value)</code>	adds value in sorted order	$O(\log N)$
<code>clear()</code>	removes all elements	$O(1)$
<code>iterator()</code>	returns iterator over elements	$O(1)$
<code>peek()</code>	returns minimum element	$O(1)$
<code>remove()</code>	removes/returns min element	$O(\log N)$
<code>size()</code>	number of elements in queue	$O(1)$

# What is a Heap?

- ▶ Kind of binary tree
- ▶ “Partially” ordered
  - ▶ Each node is smaller (higher) than both its direct children
- ▶ The tree is “filled” at all levels, and “left-padded” on the last level



# Note

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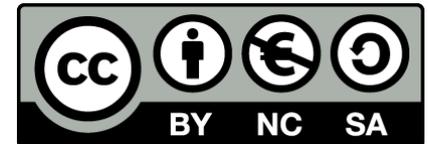
- ▶ For a priority queue to work, elements must have an **ordering**.
  - ▶ Elements must implement the **Comparable** interface (the queue will follow the natural order)

```
public class Foo implements Comparable<Foo> {  
    public int compareTo(Foo other) {  
        // Return positive, zero, or negative integer  
    }  
}
```

- ▶ Alternatively: a **comparator** must be specified in the constructor

```
public PriorityQueue(Comparator<? super E> comparator)
```

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